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Longitudinal oscillations of liquid launch vehicles due to the longitudinal instability result in additional loads of structural elements. Those dynamic loads must be considered for the strength computations of structural elements of the space stage during the design. The technique of determination of the stressed-strained state of the propellant compartment of the space stage with a complex spatial configuration under longitudinal oscillations of the launch vehicle on the active portion of the flight in operation of the cruise propulsion system of the first stage is proposed. The technique is developed by the finite element method and means of mechanical design computations (CAE Systems) and takes into account the propellant component mobility, energy dissipation of structural vibrations and liquid filling, variances in the tank wall thickness. Based on the proposed technique, the stressed-strained state of the structure of the spherically liquid-filled suspended propellant compartment of the space stage on the active portion of the flight of the three-stage launch vehicle is determined. It is shown that the maximum stress intensities of the space stage propellant compartment structure are demonstrated near points of attachment to the launcher vehicle under longitudinal oscillations of the launcher vehicle. It is found that, when the frequency of the longitudinal harmonic disturbance affecting the space stage structure is close to the frequency of the first mode of its natural longitudinal oscillations, the values of amplitudes of structural vibrations of the propellant compartment can be 10 times more than amplitudes of oscillations in points of attachment of the space stage of the launch vehicle. The proposed technique can be in progress for strength computations of space stages with complex 3D configurations under 3D oscillations of the launch vehicle.

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( 3).

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$$F \quad X \quad X_0, Y_0, Z_0; \\ F_i = [F_i^{X_0}, F_i^{Y_0}, F_i^{Z_0}], \quad x_i = [x_i^{X_0}, x_i^{Y_0}, x_i^{Z_0}], \quad X_0, Y_0, Z_0 - \\ , \quad , \quad , \\ (1), \quad \vdots$$

$$F_i = (F_i^{\max} e^{j\Psi_i}) e^{j\omega t} = (F_i^{\max} \cos \Psi_i + j \cdot F_i^{\max} \sin \Psi_i) e^{j\omega t}, \quad (2)$$

$$x_i = (x_i^{\max} e^{j\phi_i}) e^{j\omega t} = (x_i^{\max} \cos \phi_i + j \cdot x_i^{\max} \sin \phi_i) e^{j\omega t}, \quad (3)$$

$$\begin{aligned}
& j = \dots ; x_i^{\max} = i - X^{\max}, \\
& i = \dots \\
& \omega; F_i^{\max} = i - F^{\max}, \\
& x_i^{\max} \\
& \omega; \phi = \dots & i = \dots \\
& , \Psi = \dots & i = \dots \\
& \cdot \\
& (2), (3) & (1)
\end{aligned}$$

$$Q \tilde{X} = \tilde{F}, \quad (4)$$

$$Q = -\omega^2 M + j\omega C + K; \quad \tilde{X} = [\tilde{x}_1, \dots, \tilde{x}_n] \quad - \\ \tilde{x}_i; \quad \tilde{F} = [\tilde{F}_1, \dots, \tilde{F}_n] \quad - \quad \tilde{F}_i;$$

$$\tilde{x}_i = x_i^{\max} e^{j\phi_i} = x_i^{\max} \cos \phi_i + j \cdot x_i^{\max} \sin \phi_i; \quad (5)$$

$$\tilde{F}_i = F_i^{\max} e^{j\Psi_i} = F_i^{\max} \cos \Psi_i + j \cdot F_i^{\max} \sin \Psi_i. \quad (6)$$

## (4) (CAE- – Computer Aided

Engineering System) [3].

$$\tilde{\mathbf{X}} = [\tilde{x}_1, \dots, \tilde{x}_n] \quad (5),$$

$$X = [x_1, \dots, x_n],$$

$$x_i = (x_i^{\max} e^{j\phi_i}) e^{j\omega t} = \tilde{x}_i e^{j\omega t}$$

( )

$$(6) \quad \begin{aligned} X &= [x_1, \dots, x_n], \\ x_i &= (x_i^{\max} e^{j\phi_i}) e^{j\omega t} = \tilde{x}_i e^{j\omega t} \end{aligned}$$

$$\mathbf{X}^* = \mathbf{X} + \mathbf{X}^{st}.$$

$$D = DBX^* \quad (8)$$

$$, \quad , \quad X^* = \begin{matrix} n; \quad B = \\ n \times n; \quad D = \end{matrix} \quad \quad \quad n \times n .$$

$$\begin{matrix} 1 & & & 1 & & l \\ & \vdots & & & & \end{matrix}$$

$$_1 = \left[ \varepsilon_{lxx}, \varepsilon_{lyy}, \varepsilon_{lzz}, \varepsilon_{lxz}, \varepsilon_{lyz}, \varepsilon_{lxz} \right]^T, \quad (9)$$

$$\mathbf{l} = [\sigma_{lxx}, \sigma_{lyy}, \sigma_{lzz}, \sigma_{lxy}, \sigma_{lyz}, \sigma_{lxz}]^T, \quad (10)$$

$$\begin{aligned}
& \varepsilon_{lxx}, \varepsilon_{lyy}, \varepsilon_{lzz} = & , \\
& (\quad . \quad . \quad 1) & ; \quad \varepsilon_{lxy}, \varepsilon_{lyz}, \varepsilon_{lxz} = & , \\
& Y_0, \quad Y_0 & Z_0, \quad X_0 & Z_0 & ; \\
& \sigma_{lxx}, \sigma_{lyy}, \sigma_{lzz} = & - \\
& X_0, \quad Y_0, \quad Z_0 & ; \quad \sigma_{lxy}, \sigma_{lyz}, \sigma_{lxz} = & - \\
& & Y_0, \quad Z_0, \quad Z_0 & , \\
& & X_0, \quad Y_0, & ,
\end{aligned}$$

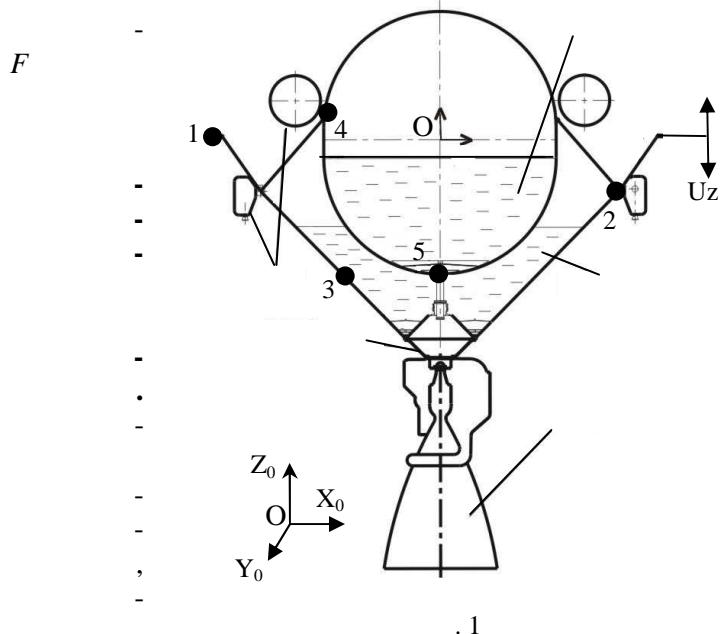
$$\varepsilon_l^i \quad \sigma_l^i$$

30

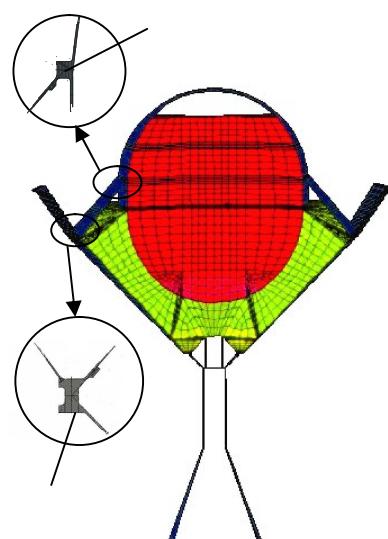
$$\varepsilon_l^i = \sqrt{2} \cdot \left( \sqrt{(\varepsilon_{lxx} - \varepsilon_{lyy})^2 + \varepsilon_{lyy}^2 + \varepsilon_{lxz}^2 + 3 * \varepsilon_{lxy}^2 / 2} \right) / 3, \quad (11)$$

$$\sigma_l^i = \left( \sqrt{(\sigma_{lxx} - \sigma_{lyy})^2 + \sigma_{lyy}^2 + \sigma_{lxz}^2 + 6 * \sigma_{lxy}^2} \right) / \sqrt{2}. \quad (12)$$

(1)



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[2],

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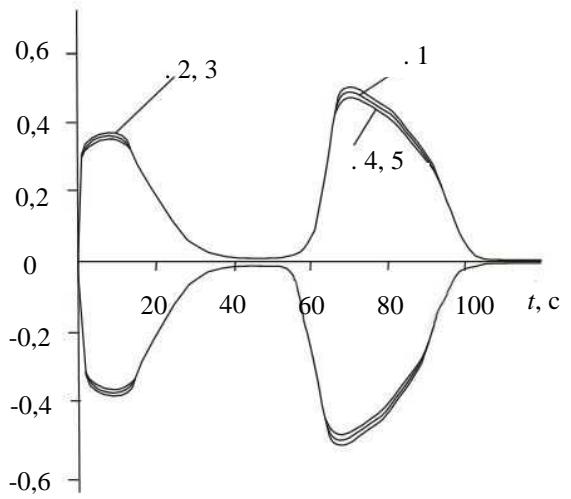
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[6].

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$A_{N_z}(t)$ , .g



8 – 10 ,

(0, 30 )

, (60 , 90 )

.3

[2],

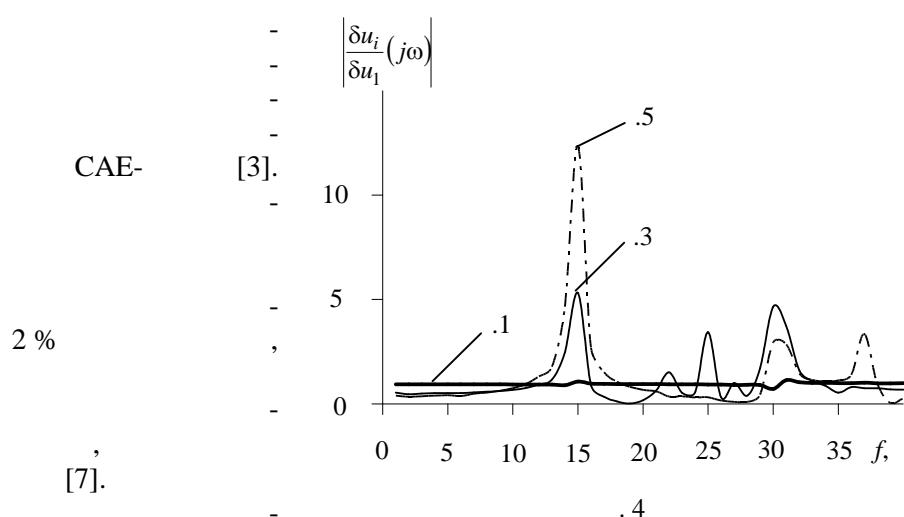
0,4 g

( .3, 1).

$n_z$ ,  
1).

0,5 g

, 9,5 0,5 g .



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 14,3 , 5 , 12 ( . . 4).  
 . 3 , « 14,3 .  
 (  $n_z$  2, 3), —  
 ( 4, 5).

CAE- 20 /  $\text{m}^2$ .

$$\varepsilon^i \quad \sigma^i \\ 9,5$$

$$A_{u_Z}(t) = A_{N_z}(t) / \omega^2 = 0,0014 \quad (A_{N_z}(t) = 0,5g)$$

. 3).

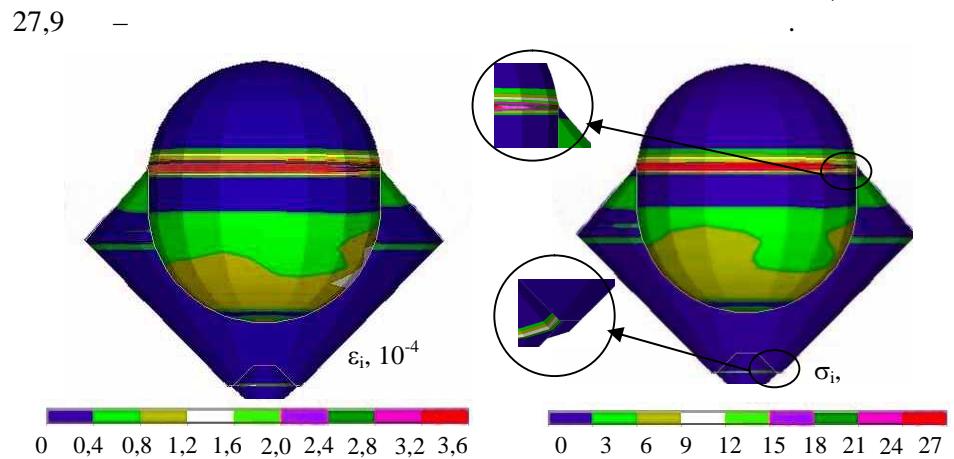
$$f_i = 14,3$$

5 ,

( . . . 3).

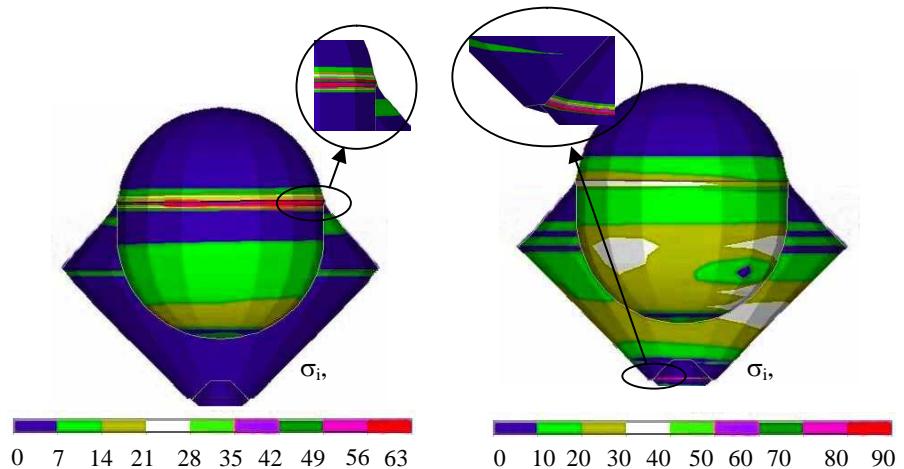
14,3 (  $A_{u_Z}(t) =$   
 $0,00069 A_{N_Z}(t) = 0,5 \text{ g}$   
 $27,9 ( A_{u_Z}(t) = 0,00016 A_{N_Z}(t) = 0,5 \text{ g} ).$

$\varepsilon^i$   
 $\sigma^i$   
 $( . . . 5 - 8)$  ,  $9,5$   $14,3$



. 5

. 6



. 7

. 8

$$\begin{array}{ccc} & ( . & . & 6, 7) \\ & 9,5 & & 14,3 \\ ( . & . & . 2). \end{array}$$

( . . . . 5 - 8)

( . . . 1).  
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1. . . . / . . . . - . : , 1969. -  
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13.03.14