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The research aim is to study oscillations of an anisotropic cylindrical shell stiffened by the longitudinal ribs with the flowing fluid in motion in loading by an axial compressive force. The least action Ostrogradsky-Hamilton principle, the method of Fourier series are used. Free oscillations of the cylindrical shell stiffened by the longitudinal ribs in the contact with the flowing fluid in motion in axial compression are studied. The motion equations are derived. In the study of the fluid motion the expression for the potential of the fluid is used. The frequency equation for the stiffened cylindrical shell in contact with the fluid in motion is derived. The numerical analysis of this problem is examined. The calculation results are presented in the form of graphs of the dependence of the frequency parameter on a relative velocity, the winding angle of the anisotropic-shell fiber and a compressive force at different relations of material elasticity moduli for an anisotropic shell.

[1, 2].

[3].

), [4, 5].

[6].

[7, 8].

[9, 10]. [11]

[12]

[13].

$xOz$  (

$$\begin{aligned}
 J = & \frac{1}{2} R^2 \int_S \{ N_{11} \varepsilon_{11} + N_{22} \varepsilon_{22} + N_{12} \varepsilon_{12} - M_{11} \chi_{11} - M_{22} \chi_{22} - M_{12} \chi_{12} \} dx dy + \\
 & + \frac{1}{2} \sum_{i=1}^{k_1} \int_L \left[ \tilde{E}_i F_i \left( \frac{\partial u_i}{\partial x} \right)^2 + \tilde{E}_i J_{yi} \left( \frac{\partial^2 w_i}{\partial x^2} \right)^2 + \tilde{E}_i J_{zi} \left( \frac{\partial^2 v_i}{\partial x^2} \right)^2 + \tilde{G}_i J_{\kappa pi} \left( \frac{\partial \varphi_{\kappa pi}}{\partial x} \right)^2 \right] dx + \\
 & + \rho_0 h \int_S \left[ \left( \frac{\partial u}{\partial t} \right)^2 + \left( \frac{\partial v}{\partial t} \right)^2 + \left( \frac{\partial w}{\partial t} \right)^2 \right] dx dy + \quad (1) \\
 & + \sum_{i=1}^{k_1} \rho_i F_i \int_L \left[ \left( \frac{\partial u_i}{\partial t} \right)^2 + \left( \frac{\partial v_i}{\partial t} \right)^2 + \left( \frac{\partial w_i}{\partial t} \right)^2 + \frac{J_{\kappa pi}}{F_i} \left( \frac{\partial \varphi_{\kappa pi}}{\partial t} \right)^2 \right] dx - \int_S q_z w dx dy - \\
 & \frac{\sigma_x h}{2} \int_0^{2\pi} \left( \frac{\partial w}{\partial \xi} \right)^2 d\theta - \frac{\sigma_x F_c}{2R} \sum_{i=1}^{k_1} \int_0^{\xi_1} \left( \frac{\partial w}{\partial \xi} \right)^2 \Big|_{\theta=0_i} d\xi,
 \end{aligned}$$

$u, v, w$  – ;  $N_{ij}, M_{ij}$  – ;  $\varepsilon_{ij}, \chi_{ij}$  –  
;  $R, h$  –  
;  $F_i, J_{zi}, J_{yi}, J_{\kappa pi}$  –  
 $i$  –  $Oz, Oy$   
;  $\tilde{E}_i, \tilde{G}_i$  –  
 $i$  – ;  $t$  – ;  $\rho_0, \rho_i$  –  
;  $\sigma_x$  – ;

$S -$  ;  $L -$  ;  $k_1 -$

$$N_{ij} = \int_{-\frac{h}{2}}^{\frac{h}{2}} (\sigma_{ij} + z w_{ij}) dz; \quad M_{ij} = \int_{-\frac{h}{2}}^{\frac{h}{2}} (\sigma_{ij} + z w_{ij}) z dz;$$

$$w_{11} = B_{11}\chi_{11} + B_{12}\chi_{22} + B_{16}\chi_{12}; \quad w_{22} = B_{12}\chi_{11} + B_{22}\chi_{22} + B_{26}\chi_{12}; \quad (2)$$

$$w_{12} = w_{21} = B_{16}\chi_{11} + B_{22}\chi_{22} + B_{66}\chi_{12}.$$

$$(2) \quad \sigma_{ij} \quad \varepsilon_{ij} \quad :$$

$$\sigma_{11} = B_{11}\varepsilon_{11} + B_{12}\varepsilon_{22} + B_{16}\varepsilon_{12};$$

$$\sigma_{22} = B_{12}\varepsilon_{11} + B_{22}\varepsilon_{22} + B_{26}\varepsilon_{12}; \quad (3)$$

$$\sigma_{12} = B_{16}\varepsilon_{11} + B_{22}\varepsilon_{22} + B_{66}\varepsilon_{12};$$

$$\varepsilon_{11} = \frac{\partial u}{\partial x}; \quad \varepsilon_{22} = \frac{\partial v}{\partial y} - \frac{w}{R}; \quad \varepsilon_{12} = \frac{\partial u}{\partial y} + \frac{\partial v}{\partial x}; \quad (4)$$

$$\chi_{11} = \frac{\partial^2 w}{\partial x^2}; \quad \chi_{22} = \frac{\partial^2 w}{\partial y^2}; \quad \chi_{12} = \frac{\partial^2 w}{\partial x \partial y}.$$

$\varphi$  ,

$$B_{11} = b_{11} \cos^4 \varphi + b_{22} \sin^4 \varphi + (b_{66} + 0,5b_{12}) \sin^2 2\varphi;$$

$$B_{22} = b_{11} \sin^4 \varphi + b_{22} \cos^4 \varphi + (b_{66} + 0,5b_{12}) \sin^2 2\varphi;$$

$$B_{12} = (b_{11} + b_{22} - 4b_{66}) \sin^2 \varphi \cos^2 \varphi + b_{12} (\sin^4 \varphi + \cos^4 \varphi);$$

$$B_{66} = -(b_{11} + b_{22} - 2b_{12}) \sin^2 \varphi \cos^2 \varphi + b_{66} \cos^2 2\varphi;$$

$$B_{26} = \frac{1}{2} (b_{22} \cos^4 \varphi - b_{11} \sin^2 \varphi) \sin 2\varphi - \frac{1}{6} (b_{12} + 2b_{66}) \sin 4\varphi;$$

$$B_{16} = \frac{1}{2} (b_{22} \sin^2 \varphi - b_{11} \cos^2 \varphi) \sin 2\varphi - \frac{1}{6} (b_{12} + 2b_{66}) \sin 4\varphi,$$

$b_{11}, b_{12}, b_{12}, b_{66} -$

;  $\varphi -$  , ( )

$$\delta W = 0, \quad (5)$$

$$W = \int_{t'}^{t''} L dt -$$

,  $L -$

,  $t', t'' -$

$\varphi$  [3]

$$\Delta\varphi - \frac{1}{a_0^2} \left( \frac{\partial^2 \varphi}{\partial t^2} + 2U \frac{\partial^2 \varphi}{R \partial \xi \partial t} + U^2 \frac{\partial^2 \varphi}{R^2 \partial \xi^2} \right) = 0. \quad (6)$$

[3, 11]:

$$\mathfrak{D}_r \Big|_{r=R} = \frac{\partial \varphi}{\partial r} \Big|_{r=R} = - \left( \omega_0 \frac{\partial w}{\partial t_1} + U \frac{\partial w}{R \partial \xi} \right). \quad (7)$$

$q_z$

$$q_z = -p. \quad (8)$$

(7), (8)

(1),

(6),

$$\begin{aligned} u &= u_0 \sin \chi \xi \cos n\theta \sin \omega_1 t_1; \\ v &= v_0 \sin \chi \xi \cos n\theta \sin \omega_1 t_1; \\ w &= w_0 \sin \chi \xi \cos n\theta \sin \omega_1 t_1, \end{aligned} \quad (9)$$

$u_0, v_0, w_0$  -

;  $\chi, n$  -

$$; t_1 = \omega_0 t; \omega_0 = \frac{1}{R} \sqrt{\frac{E_1}{(1-v^2)\rho_0}}.$$

$\varphi$  :

$$\varphi(\xi, r, \theta, t_1) = f(r) \cos n\varphi \sin kx \sin \omega t. \quad (10)$$

(10),

(6) (7) :

$$\varphi = -\Phi_{\alpha n} \left( \omega_0 \frac{\partial w}{\partial t_1} + U \frac{\partial w}{R \partial \xi} \right); \quad (11)$$

$$p = \Phi_{\alpha n} \rho_m \left( \omega_0^2 \frac{\partial^2 w}{\partial t_1^2} + 2U \omega_0 \frac{\partial^2 w}{R \partial \xi \partial t_1} + U^2 \frac{\partial^2 w}{R^2 \partial \xi^2} \right),$$

$$\Phi_{\alpha n} = \begin{cases} I_n(\beta r), & M_1 < 1; \\ J_n(\beta_1 r), & M_1 > 1; \\ \frac{R}{n}, & M_1 = 1; \end{cases} \quad (12)$$

$$M_1 = \frac{U + \omega_0 R \omega_1 / \alpha}{a_0}; \quad \beta = \frac{\chi}{R} \sqrt{1 - M_1^2}; \quad \beta_1 = \frac{\chi}{R} \sqrt{M_1^2 - 1}; \quad I_n -$$

$$(8) \quad q_z = -p, \quad p -$$

$$(9) \quad p$$

$$p = \frac{\rho_m \Phi_{\alpha n}}{\rho_0 \omega_0^2 h} (\omega_0^2 \omega_1^2 + 2\omega_0 \omega_1 \chi U + \chi^2 U^2) w. \quad (13)$$

(9), (13) (5)

$$a_{i1} u_0 + a_{i2} v_0 + a_{i3} w_0 = 0 \quad (i = 1, 2, 3). \quad (14)$$

$$a_{i1}, a_{i2}, a_{i3} \quad (i = 1, 2, 3)$$

$$(14) \quad \omega_1,$$

$$(14) \quad \omega_1, \quad \omega_1.$$

$$\omega_1, \quad \omega_1$$

$J_n$ :

$$\begin{vmatrix} 2(\tilde{\varphi}_{11} - \psi_{11} \omega_1^2) & \tilde{\varphi}_{44} & \tilde{\varphi}_{55} \\ \tilde{\varphi}_{44} & 2(\tilde{\varphi}_{22} - \psi_{22} \omega_1^2) & \tilde{\varphi}_{66} \\ \tilde{\varphi}_{55} & \tilde{\varphi}_{66} & 2(\tilde{\varphi}_{33} - \psi_{33} \omega_1^2 + q_z^{(0)} \psi_2) \end{vmatrix} = 0. \quad (15)$$

$$U = 0 \quad (15)$$

$$F_i = 3,4 \quad ; \quad J_{yi} = 5,1 \quad ; \quad \rho_0 / \rho_m = 0,105; \quad \rho_0 = \rho_i = 0,26 \cdot 10^4 \text{ N}^2 / \text{m}^4;$$

$$J_{yi} = 5,1 \quad ; \quad h = 1 \quad ; \quad h_i = 1,39 \quad ; \quad L = 10 \quad ; \quad b_{11} = 18,3 \quad ;$$

$$b_{12} = 2,77 \quad ; \quad b_{22} = 25,2 \quad ; \quad b_{66} = 3,5 \quad ; \quad \frac{l_{\kappa \rho i}}{2\pi R^3 h} = 0,5305 \cdot 10^{-6}.$$

$$. 1 \quad \omega_1$$

$$U^* = U / c, \quad c = \omega_0 R \quad \chi = 1, \quad n = 4, \quad \varphi = 0,6;$$

. 2 -

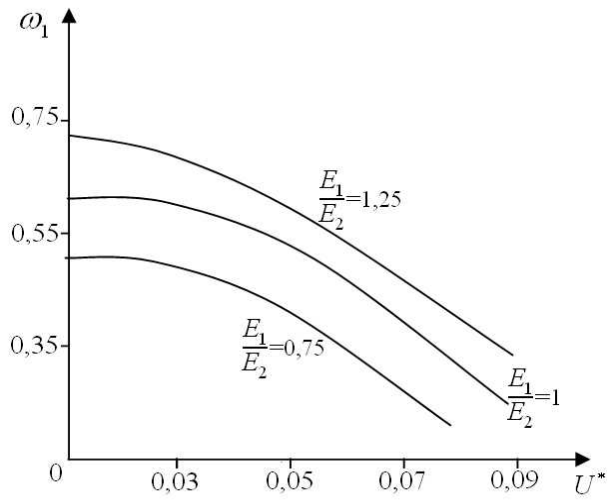
$$\varphi \quad \frac{R}{h}; \quad . 3 -$$

$$\omega_1 \quad ( \quad n = 4, \quad k_1 = 4, \quad U^* = 0,06)$$

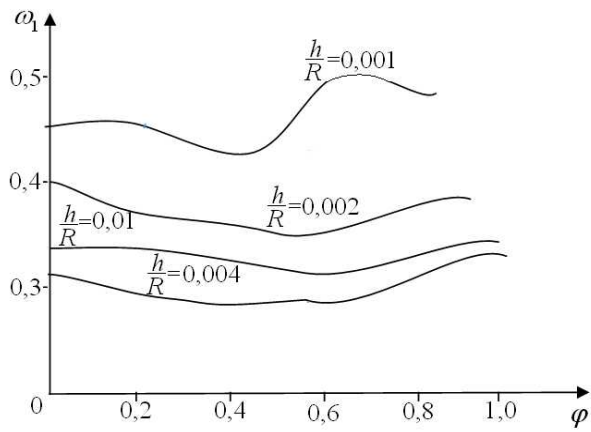
$E_2 -$

( $E_1$

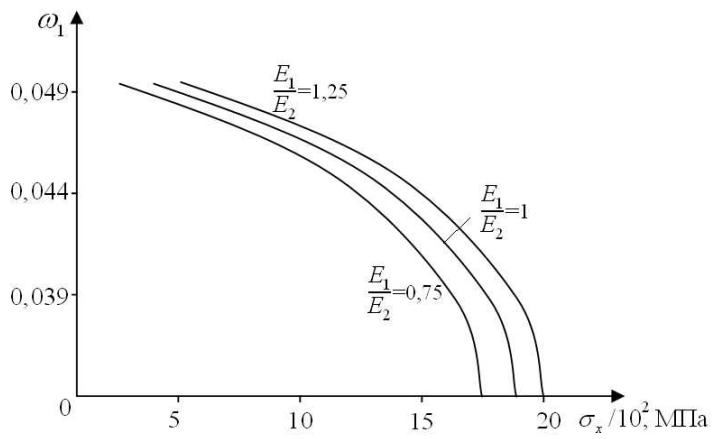
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